





# THE NEXT GENERATION OF CRANE PERFORMANCE

**INDUSTRY-LEADING SAFETY AND** PERFORMANCE FEATURES COMBINE WITH **OUR SUPERIOR APPLICATION EXPERTISE TO** PROVIDE UNMATCHED PERFORMANCE.

IMPULSE drives are designed especially for material handling applications, providing a complete package of crane-specific capabilities far beyond a general purpose drive's functionality.

Safety features are integrated into every drive, preventing harm to the crane structure and crane equipment, and most importantly, creating a safe working environment for operators.

Magnetek's IMPULSE•G+/VG+ Series 4 drives continue our tradition of providing the most reliable and costeffective adjustable frequency crane controls available. With hundreds of thousands of drives in operation backed by decades of experience, IMPULSE drives are the smart choice.



# INDUSTRY-LEADING PERFORMANCE FEATURES

LOAD CHECK II™ continuously detects hoist overload conditions, halting upward motion and only allowing the load to be lowered. Load Check II continuously monitors the hook load, both during acceleration and constant speed, eliminating the need for load cells in most applications. It provides an auto-setup function which defines the hoist's maximum hook load in seconds. With these control advancements, the drive no longer pauses for tests unless rated capacity is approached, providing increased productivity.

SAFE TORQUE OFF provides a redundant hardware safety circuit that guarantees motor and brake power are removed when an E-STOP switch or safety controller opens the drive input, eliminating the need for external disconnects. This functionality is provided in a safety category 3 architecture and designed to PLd and SIL CL2 according to ISO/EN 13849-1 and IEC/EN 62061 respectively, meeting the requirements of IEC/EN 61508.

ADAPTIVE ULTRA-LIFT™ allows for hoist operation above base speed with a light load or empty hook. Adaptive Ultra-Lift continuously monitors motor torque and adjusts motor speed to operate at peak performance, improving plant safety and maximizing throughput. For example, motor speed can now be increased automatically when a magnet releases a load or gear ratios change with overwrapping drums.

BRAKE TEST verifies brake torque with the press of a button, capturing breakaway torque with a monitor parameter on the keypad. This valuable tool determines the condition of the brake so you can perform preventative maintenance and quickly commission the crane.

ANTI-SHOCK automatically stabilizes loads by detecting and minimizing rapid increases in motor torque, thus reducing the potential for crane damage caused by operator induced load shock.

QUICK-SETUP™ is provided by the easy-to-use keypad and X-Press Programming™ so you get up and running right away. X-Press Programming automatically configures several commonly used parameters and features when a control method, motion, or speed reference is selected.

SAFE LIFTING features are built right in, including Torque Proving, which confirms the motor is providing enough torque to safely lift a load prior to releasing the brake. Torque Limiting prevents the crane from performing a lift that could overload the motor and cause mechanical fatigue. Brake Integrity Check tests the primary and emergency brakes to ensure they are mechanically capable of holding the load.

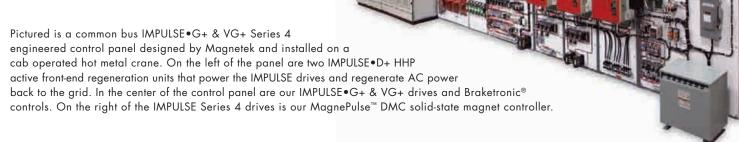
OPTION CARDS provide the drive flexibility needed with expandable AC, DC digital and analog input and output option cards. Simplify automation and diagnostics integration with our EtherNet/IP, Modbus TCP/IP, PROFIBUS-DP, and PROFINET option cards. The new control power supply option maintains drive diagnostics, I/O, and communications when main power is disconnected from the drive.

# IMPULSE • LINK DIAGNOSTIC SYSTEM

maximizes the efficiency of your drive by providing easy parameter management right on your PC. IMPULSE•Link can communicate with up to 31 drives locally or wirelessly, allowing drive diagnostics, monitoring, and programming.

ENERGY ENGINEERED™ motion control products from Magnetek are designed to efficiently utilize available power, reducing energy costs for you and your customers.

RELIABILITY Magnetek drives are designed with reliability and economy in mind. The hardware and software were designed and extensively tested specifically for the operating conditions seen in overhead material handling applications. These durable drives feature new power modules that can withstand four times more thermal cycles than previous generations. Preventative maintenance monitors provide the feedback you need to proactively schedule maintenance and minimize downtime. IMPULSE•G+ & VG+ Series 4 drives are backed by our industry-leading three-year warranty.





# CUSTOM CONTROL PANELS

Magnetek's custom control panels with IMPULSE•G+ and VG+ Series 4 drives provide the ultimate solution for overhead material handling. These panels are custom designed and built to your specifications to meet your exact application requirements. Our experienced engineering staff provides technical support and extensive overhead material handling expertise when quoting and designing your project. Custom panels are available with an unlimited number of configurations, components, and accessories.

# COMMON OPTIONS INCLUDE:

- 120V control transformer and interface card\*
- Brake contactor
- Built-in electronic motor thermal overload protection
- Clearly marked wires (at both ends)
- Wiring diagram
- NEMA 4/12 enclosure
- Enclosures for caustic and other environments
- Wiring for radio remote controls
- NEMA brake contactors

We can design a system to fit your application. Contact the factory for information.

\*24 VDC, 24 VAC, and 42-48 VAC optional

- Load and line reactors
- Air-conditioning or cooling fans
- Heaters and thermostats
- Door mounted keypads
- UL 508 certification



# KEYPAD WITH DIGITAL DISPLAY

Our user-friendly keypad gives you five lines of 16 characters each and includes soft keys and upgraded parameter selection. The display makes navigation and reading diagnostics even easier.

### **ALLOWS FOR:**

- Programming various drive parameters
- Parameter back-up (store and copy)
- Monitoring functions of the drive
- Reading of alpha-numeric fault diagnostic instructions
- Remote monitoring



# FEATURES BENEFITS

# **SAFETY**

Brake Test\* Allows testing of available brake torque Anti-Shock\* Minimizes harmful torque increases due to load shock, reducing potential for equipment damage Encoder Loss Detection\* Signal loss detection at all times, even when the motor is not rotating (load float) Snapped Shaft Detection\* Detects a broken coupling shaft or discontinuity in the drive train Roll Back Detection/Torque Proving Drive monitors brake functionality and motor torque at start and stop; the drive will maintain control of the load in at Start/Brake Check at Stop case of a brake failure Safe Operating Windows Reduces the possibility of programming unsafe parameters Load Check II™ Continuously detects hoist overload conditions Quick Stop™ Reduces the possibility of load and crane collision Slack Cable Detection Provides annunciation of the slack cable condition to the operator Multi-Level Password Protection Limits unauthorized modification of drive parameters Phase Loss Detection In case of output phase loss, brake will set immediately, retaining load Control Interface Optically isolated quick disconnect 120 VAC control interface with parameter backup UL/cUL Rated Tested and listed by Underwriters Laboratory Safe Torque Off Redundant crane monitoring circuits can externally stop the drive to safety category 3 Ground Fault Short Circuit Protection Reduces damage to motor and drive Indicates when the DC BUS has discharged to a safe level DC BUS Charge Indicator

# PERFORMANCE

Indexing\* Allows precise, programmed motor movement Load Sharing\* Allows two or more mechanically coupled motors to be controlled in a master/slave torque control fashion Hook Height Measurement\* Uses an incremental encoder signal to determine hook height from a calibrated position Electronic Programmable Limit Switch\* Allows slow down and stop limits without a geared limit switch Automatic Reset Allows selectable conditions to be automatically reset with a new run command Over-Torque/Under-Torque Detection Allows programmable outputs and actions based on torque conditions Automatically compensates for motor slip Slip Compensation Motor Lead Reversal Electronically swaps motor leads for reverse operation Copy, store, and write parameters to/from keypad Keypad Copy Communication Built-in RS-485 communication (Modbus - RTU) Static Auto-Tune Allows auto-tune without mechanical disconnection Enhanced Keypad Display Easily navigate and read diagnostics Allows a load to be held aloft at zero speed without setting the electric brake Load Float™ Weight Calculation\* Enables load weight to be calculated with an accuracy of  $\pm 5\%$  of full load (0-10 VDC Output) X-Press Programming™ Allows programming initial setup in seconds Swift-Lift™/Ultra-Lift™ Allows overspeeding with light loads or empty hook Reverse Plug Simulation™ Allows operator to smoothly and quickly stop and change directions without setting parking brake Stall Prevention Extends acceleration time and prevents the motor torque limits from being exceeded Micro-Speed™ Allows operator to make precise, slow movements Multi-Function Input Terminals Set end of travel/slow down limits or other functions Flash Memory Stores last ten fault occurrences, even after power-down, for diagnostic purposes Elapsed Time Counter Indicates actual time of operation (power on or run time)

# RELIABILITY

Preventative Maintenance Monitors	Perform drive maintenance before a failure to minimize downtime
Programmable Fan	Cooling fan on/off control selections for longer life
Ambient Compensated Overload	High ambient motor protection
Increased Drive Output Current Ratings	Designed for 2x longer life than previous models including 4x longer power module life
Built-in Auto-Tune	Maximizes performance and minimizes power leakage through (static or rotational) auto-tuning to extend motor life
Communications	Provides reliable digital link among various crane system peripherals, including Modbus RTU, PROFIBUS-DP, PROFINET, and Ethernet/IP, Modbus TCP/IP
Operation/Fault Display	Simplifies setup and troubleshooting

\* Features available on IMPULSE•VG+ only



# SPECIFICATION VALUE AND INFORMATION

Certification	UL, cUL, CSA, RoHS (CE available with filters)
Rated input power supply volts and frequency	3-phase 200–240 VAC, 380–480 VAC, or 500-600 VAC; 50 or 60Hz
Allowable input voltage fluctuation	+10% or -15% of nominal, 3-phase
Allowable input frequency fluctuation	±5% of nominal
Control method	Fully digital; sine-wave, V/F control, open loop vector control, flux vector control
Maximum output voltage (VAC)	Max output voltage 3-phase, 200/208/230/240/380/400/415/440/460/480/500/575/600V (proportional to input voltage)
Rated output frequency (Hz)	0 to 150 Hz (consult factory for applications above 150 Hz)
Output frequency accuracy	0.01% with digital reference command, -10° to 40°C; 0.1% with analog reference command; 10 bits/10V; 25°C, ±10°C
Frequency reference resolution	Digital: 0.0Hz; analog: 0.03Hz (at 60Hz)
Output frequency resolution	0.0Hz
Overload capacity	150% of rated load for 1 minute
Remote frequency reference sources	0-10 VDC (20Ω); 4-20mA (250Ω); ±10 VDC; serial (RS-485)
Acceleration/deceleration times	0.1 to 25.5sec — 4 sets; all independently adjustable
Braking torque	150% or more with dynamic braking (optional)
Motor overload protection	Electronic thermal overload relay; UL recognized (I2T)
Overcurrent protection level (OC)	200% of rated current
Circuit protection	Ground fault and blown-fuse protection
Overvoltage protection level	410 VDC (230V), 820 VDC (460V), 1040 VDC (575V)
Undervoltage protection level	190 VDC (230V), 380 VDC (460V), 475 VDC (575V)
Heatsink over temperature	Thermostat trips between 115-145°C
Four quadrant torque limit selection	Separate functions for FORWARD, REVERSE, and REGEN; all selectable from 0–300%
Stall prevention	Separate functions for acceleration, at-speed and constant horsepower regen
Other protection features	Speed deviation, overspeed, mechanical brake failure, lost output phase, lost input phase, failed-oscillator, PG-disconnect, mechanical overload, roll-back detection, internal braking transistor failure, and built-in watchdog
DC bus voltage indication	Charge LED is on until DC bus voltage drops below 50 VDC
Location	Indoors; requires protection from moisture, corrosive gases and liquids
Ambient operating temperature	14° to 140°F (-10° to 60°C). Consult factory for high ambient applications
Storage temperature	-4° to 158°F (-20° to 70°C)
Humidity	95% relative; noncondensing
Vibration	1G for 10-20Hz 0.6G for 20-55Hz (2003-2180, 4001-4150, 5001-5077) 0.2G for 20-55Hz (2215-2415, 4180-41090, 5099-5200)
Elevation	3300 ft. (1000 m) or less 9900 ft. (3000 m) or less with current derating
Safety standard	UL 508C

# **CAPABILITIES**

# IMPULSE • G+ SERIES 4

## **RATINGS**

200-240 VAC, 3.0 to 415A (0.4 kW/0.75 HP to 110kW/150 HP)

380-480 VAC, 1.8 to 1090A (0.4 kW/0.75 HP to 560kW/900 HP)

500-600 VAC, 1.7 to 200A (0.75 kW/1 HP to 160 kW/200 HP)

## CLASS OF SERVICE

CMAA Class A-F Service AISE TR6 Class 1 to 4 ASME HST-4M H1 to H5

### SPEED RANGE

40:1 in V/F Mode (15 preset V/F Patterns, 1 Adjustable) 200:1 in Open Loop Vector Mode

# SPEED CONTROL METHODS

Up to 17 Distinct Speeds (Stepped)

2-Step Infinitely Variable

3-Step Infinitely Variable

Analog Signal (0-10 VDC, 4-20mA, ±10 VDC)

Digital Pulse Train Input (32kHz max)

Radio Drive Serial Interface (RDSI)

#### PROGRAMMABLE TERMINALS

- (8) 120 VAC Inputs (24 VAC, 42-48 VAC, or 24 VDC optional) Compatible with 50 Hz and 60 Hz
- (3) Digital Dry Contact Relay Outputs (1A max @ 250 VAC, 1A max @ 30 VDC, Form A)
- (1) Dedicated Fault Relay Output (1A max @ 250 VAC, 1A max @ 30 VDC, Form C)
- (3) Analog Inputs (0-10 VDC and ±10 VDC (20K  $\Omega$ ), 4-20mA (250  $\Omega$ ))
- (2) Analog Outputs (0-10 VDC and  $\pm 10$  VDC max current 2mA, 4-20mA (500  $\Omega$ ))

(Consult factory for additional analog/digital input/output option cards)

## **APPLICATIONS**

Worm Gear and Mechanical Load Brake Hoists Traverse Motions

# IMPULSE • VG+ SERIES 4

#### **RATINGS**

200-240 VAC, 3.0 to 415A (0.4 kW/0.75 HP to 110kW/150 HP)

380-480 VAC, 1.8 to 1090A (0.4 kW/0.75 HP to 560kW/900 HP)

500-600 VAC, 1.7 to 200A (0.75 kW/1 HP to 160 kW/200 HP)

## **CLASS OF SERVICE**

CMAA Class A-F Service AISE TR6 Class 1 to 4 ASME HST-4M H1 to H5

## SPEED RANGE

1500:1 in Flux Vector Mode

## SPEED CONTROL METHODS

Up to 17 Distinct Speeds (Stepped)

2-Step Infinitely Variable

3-Step Infinitely Variable

Analog Signal (0-10 VDC, 4-20mA, ±10 VDC)

Digital Pulse Train Input/Output (32kHz max)

Radio Drive Serial Interface (RDSI)

#### PROGRAMMABLE TERMINALS

- (8) 120 VAC Inputs (24 VAC, 42-48 VAC, or 24 VDC optional) Compatible with 50 Hz and 60 Hz
- (3) Digital Dry Contact Relay Outputs (1A max @ 250 VAC, 1A max @ 30 VDC, Form A)
- (1) Dedicated Fault Relay output (1A max @ 250 VAC, 1A max @ 30 VDC, Form C)
- (3) Analog Inputs (0-10 VDC and  $\pm 10$  VDC (20K  $\Omega$ ), 4-20mA (250  $\Omega$ ))
- (2) Analog Outputs (0-10 VDC and  $\pm 10$  VDC max current 2mA, 4-20mA (500  $\Omega$ ))
- (1) Single line driver/open collector encoder option card with 5/12 VDC (200mA) power supply

(Consult factory for additional analog/digital input/output option cards)

#### **APPLICATIONS**

Non-Mechanical Load Brake Hoists Traverse Motions (Consult factory)



# **CUSTOMIZATION OPTIONS**

# INTERFACE CARDS

Optically-isolated interface of 8 digital inputs (binary), 3 Form A dry contact digital outputs, 1 Form C dry contact fault output, 3 analog inputs, 2 analog outputs, pulse input and feedback, and RS-485 Modbus RTU interface.

DIGITAL INPUT OPTIONS 120 VAC/50Hz & 60Hz 42-48 VAC/50Hz & 60Hz 24 VAC/50Hz & 60Hz 24 VDC

# INPUT/OUTPUT OPTIONS

#### **ANALOG INPUTS**

(13 Bit + Sign) – Interface of 3 high resolution analog inputs to the drive. Signal levels (individually selectable): 0 to  $\pm$  10 VDC (20kOhm) or 4 to 20mA (500 Ohm).

Input resolution: Voltage (1/8192), Current (1/6654).

#### **AC DIGITAL INPUTS**

(4 Channels) – Optically-isolated interface of 4 digital inputs (binary) to the drive.

#### **OPTIONS**

120 VAC/50Hz & 60Hz 42-48 VAC/50Hz & 60Hz 24 VAC/50Hz & 60Hz

# INPUT/OUTPUT OPTIONS (CONTINUED)

### **AC DIGITAL INPUTS & OUTPUTS**

(4 Channels) – Optically-isolated interface of 4 digital inputs (binary) to the drive and 4 1A Form A dry contact relay outputs.

#### **OPTIONS**

120 VAC/50Hz & 60Hz 42-48 VAC/50Hz & 60Hz 24 VAC/50Hz & 60Hz

## **DC DIGITAL INPUTS**

(16 Channels) – 24 VDC optically-isolated interface of 16 digital inputs (binary) to the drive.

# **ANALOG OUTPUTS**

(11 Bit + Sign) – Two signals for remote metering of any two of the drive's "U1" monitors and is additive to the two standard analog outputs. Signal level: 0 to +/- 10 VDC (20kOhm).

#### **DIGITAL OUTPUTS**

(8 Channels) – Eight additional digital outputs for use in monitoring the status outputs of the drive. Signal levels: 2 channels of Form A, 250 VAC, 30 VDC, 1A and 6 channels of PHC, 48 VDC, 50 mADC, Shared Common.

# CONTROL OPTIONS

### SINGLE ENCODER—LINE DRIVER

Providing velocity and direction feedback from an encoder, this option is used for motor speed feedback in closed loop flux vector control. A 5 VDC buffered output is also included. Signal levels: 5 or 12 VDC differential line driver with compliments, maximum input frequency of 300kHz, phases A and B.

## SINGLE ENCODER—OPEN COLLECTOR

This option provides velocity and direction feedback from an encoder and provides motor speed feedback in closed loop flux vector control. A 24 VDC buffered output (open collector) is also included. 32kHz maximum input frequency.

# 24 VDC CONTROL POWER UNIT

This option provides board-level component voltages for the drives when provided with 24 VDC from an external, customer-supplied source. It is used to maintain both drive control power and network communications (when utilized).

### **IMPULSE SERIES 4 REMOTE OPERATOR KIT**

The IMPULSE Series 4 Remote Operator Kit allows the LCD Operator to be mounted to an enclosure door. The kit includes one LCD Operator, one mounting bracket, and one RJ-45 cable.

### **USB COPY STICK**

The USB Copy Stick allows the drive to connect to the USB port on a PC. It can read, copy, and verify drive parameter settings from one drive to another like drive.

## USB Copy Unit Kit Contents:

- 1 USB Copy Unit (Y-Stick)
- 1 1 ft. USB Cable to connect PC to Y-Stick
- 1 3 ft. Cable with RJ-45 connector on both ends to connect Y-Stick to drive

Driver: USB Copy Stick Driver\*

# NETWORK COMMUNICATIONS OPTIONS

# ETHERNET/IP

Allowing for communication over 10/100Mbps Ethernet networks, this option has the ability to configure the IP address from a user specified IP address, from a DHCP host, or from a BootP host. All parameters, diagnostics, and operational commands are accessible via EtherNet/IP.

# **MODBUS TCP/IP**

This option complies with the Modbus TCP/IP protocol specification and allows for Modbus communication over 10/100Mbps Ethernet networks. The IP Address can be configured from a user specified IP address, from a DHCP host, or from a BootP host. All parameters, diagnostics, and operational commands are accessible via Modbus TCP/IP. Up to 10 simultaneous PLC/PC connections are supported.

## **PROFINET**

This option complies to PROFINET I/O device and PROFIDrive profile specifications. It allows connection to a PROFINET network and facilitates the exchange of data via a simple networking solution that reduces the cost and time to wire and install factory automation devices, while providing interchangeability of like components from multiple vendors. This is a PROFINET Conformance Class A certified interface.

#### PROFIBUS-DP

This option complies with the Profibus–DP protocol specification. All parameters, diagnostics, and operational commands are accessible via Profibus. The option board provides a 9-pin (F) type D-Sub connector for easily connecting to a standard Profibus–style, shielded twisted-pair cable. Each Profibus network supports up to 99 drives. All of the Profibus data rates from 9.6Kbps to 12Mbps are supported. The option is configured using parameters within the drive, which allows for easy configuration eliminating the use of hardware switches. Status LEDs are viewable through the front cover, and a monitor has been added to allow for improved diagnostics.



<sup>\*</sup>Note: This driver is required to be installed on the PC before the Copy Stick can be used.



# DIAGNOSTICS AND DRIVE SUPPORT TOOLS

# IMPULSE • LINK DIAGNOSTIC SOFTWARE

- Parameter Management
- Drive Monitor
- DataLogger
- Drive Trending Tool

# **DATALOGGER SERIES 4**

- Easily access Run, Alarm, and Fault histories, drive parameters, and drive trending data
- View data and analysis via the LCD scrolling display or on your PC
- Compatible with IMPULSE® Series 4, Series 3, and G+ Mini drives

## CRANE MONITORING

IMPULSE G+/VG+ drives can be the cornerstone of an automated material handling system providing advanced diagnostic capabilities including:

- Human Machine Interface (HMI)
- Peripheral Equipment Interface
- Workflow Monitoring
- Material Tracking
- Wireless Data Transfer
- RF Communication

Our highly trained team can assess your application and offers solutions to enhance system diagnostics, prevent equipment damage, and simplify maintenance, troubleshooting, and overall operation.



# CUSTOM APPLICATION SOFTWARE

Our software will save you money by eliminating the need for a PLC or additional external logic.

These software applications can be added to our already robust IMPULSE drives to meet your unique application requirements.

FOOTBRAKE/STATIC STEPLESS SIMULATION SOFTWARE

**BUCKET CONTROL SOFTWARE** 

DRIVE SYNCHRONIZATION SOFTWARE

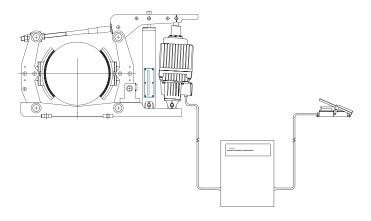
SWAY CONTROL SYSTEM (SCS®) SERIES 2



# FOOTBRAKE/STATIC STEPLESS SIMULATION SOFTWARE

This software is designed for use on traverse motions to provide an effective means to slow or stop the motion of the bridge or trolley. Encoder feedback is used to determine bridge or trolley speed at all times, allowing the operator to smoothly re-initiate a run command to a coasting crane. This prevents the jerking motions and slow responsiveness found with acceleration and deceleration ramps.

Improved torque control ensures a smooth transition from coasting to slowing down and is non-destructive to the controls or the crane itself. As more torque is applied, the crane will accelerate or decelerate faster. An optional input to the drive while the footbrake is applied prevents the motor from driving into the brake, saving wear and tear.



### APPLY THIS SOFTWARE TO:

- New or existing cab controlled cranes
- Existing hydraulic brakes
- Footbrakes
- Static stepless retrofits
- Braketronic®

#### STATIC STEPLESS SIMULATION SOFTWARE:

- Eliminates current spikes and excess mechanical torque/stress on the drive train and allows quick but smooth starting or changing of direction
- Reduces maintenance costs, with fewer moving parts that wear and require replacing, like contactor tips, brake pads, etc.
- Provides higher reliability with digital technology
- Improves diagnostics and troubleshooting of any fault and alarm conditions with the keypad, fault history, DataLogger, and IMPULSE\*Link for diagnostics and support tools
- Interfaces to the Induction Master joystick with IVM Board, making a retrofit easy
- Gives operators ultimate control and the same feel to which they are accustomed
- Utilizes standard squirrel cage motor or existing wound rotor



# BUCKET CONTROL SOFTWARE

# SAVE TIME AND MONEY WITH OUR BUCKET CONTROL CUSTOM SOFTWARE

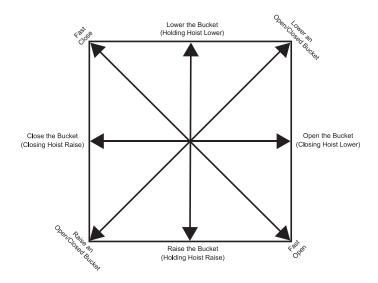
This custom software can be used with IMPULSE•VG+ Series 4 drives to control multi-line clamshell or grapple buckets that utilize a loading/closing hoist. Although the open and hold drives operate independently, the software lets you control the various motions of the bucket without the need for a PLC.

It features Bucket Position Indication, which provides the operator with the open/close status of the bucket while dredging (underwater) or when the bucket is not visible. This is done via analog output from the closing hoist and is received by an analog meter or by an MMI.

No communication (such as master/slave) is needed. In order to maintain the bucket in the open position while lowering, both hoists must operate at the same speed. In order to keep a full bucket closed while raising it out of the pile, torque must be proportionally shared between the two hoists.

# **USE BUCKET CONTROL SOFTWARE\* TO:**

- Lower an open bucket
- Close the bucket on a pile
- Raise a closed bucket
- Raise an open bucket
- Perform horizontal winch applications



<sup>\*</sup> Requires a Uni-Polar Analog Master Switch or Multi-Step Digital Speed/Torque References

# DRIVE SYNCHRONIZATION SOFTWARE

# SYNCHRONIZATION SOFTWARE MAKES IT EASY!

This custom software allows you to synchronize multiple IMPULSE •VG+ Series 4 drives. The slave drives utilize an encoder option board with two encoder inputs and monitor both its own encoder feedback AND the master's encoder feedback, while also sending timing status information back to the master. The slave compensates for any position errors by adjusting its motor speed, resulting in near-perfect alignment between the master and slave motor shafts. The slave drive also possesses the ability to automatically re-synchronize the motors and has an electronic gearing feature. While both drives are running, there is no accumulation of position error, so alignment is always maintained.



#### YOU CAN:

- Operate a multiple hoist application independently or synchronized
- Synchronize a cable reel to a hoist
- Synchronize multiple trolleys on a single bridge
- Synchronize multiple motions between 2 or more cranes

## DRIVE SYNCHRONIZATION SOFTWARE:

- Offers increased safety by precisely controlling motion and preventing the operator from making an uneven lift
- Saves time and money by eliminating the need for a PLC
- Increases productivity because the operator does not need to level the hoists manually

# DRIVE SYNCHRONIZATION SOFTWARE\* MAY BE APPLIED ON:

- Speed matching two or more independent systems, such as independent hoists, bridges, or trolleys that are not mechanically linked or bound together
  - System needs to be able to correct error without being mechanically bound (i.e. through the wheels of an end truck)
- Bridge applications where two synchronized motors are driving opposite end trucks (does not automatically compensate for skew)

PERFORMANCE FEATURES	BENEFITS
Position error stored at power down	Motions can be automatically re-synchronized even after a power down, without the need for re-homing or calibrating synchronized hook offsets
Multiple gear ratios	Allows motions with different hook speeds, like gearing, and encoder PPRs
Advance/retard function	The user can very easily fine position one or multiple motions
Availability of software features	Standard crane & hoist software features (such as Adaptive Ultra Lift <sup>TM</sup> , Load Check II <sup>TM</sup> , Weight Measurement & more) are available even while utilizing the Drive Synchronization software. Must be specified at the time of order

Drive synchronization software should NOT be applied on:

- Load sharing applications with two or more mechanically coupled systems. This includes directly coupled motor shafts, trolleys, or bridges that are mechanically coupled together or two or more motors that are indirectly tied together through a structure, such as a bridge or trolley.
- Driving two or more wheels on the same rail, such as the swing motion on a log handling crane, or a bridge motion on a polar crane. In these cases, the "Load Share" feature within Magnetek's standard IMPULSE Crane & Hoist software is a better solution.
- \*Note: Because customers may not be familiar with programming application specific software of this nature, Magnetek strongly recommends and may in some cases require that the purchaser use Magnetek's Field Service Personnel for initial startup as part of the purchase. Please consult factory for additional information.



# SWAY CONTROL SYSTEM (SCS®) SERIES 2

# ENHANCE CRANE OPERATION WITH MAGNETEK'S SWAY CONTROL SYSTEM

This custom software is embedded in our IMPULSE•G+ Series 4 variable frequency drives for new or existing crane control systems without the need for external programmable logic controllers or costly height measurement devices.

### SCS SERIES 2 BENEFITS:

- Improves productivity by allowing the crane operator to concentrate on load engagement/disengagement rather than focusing on minimizing load swing. The system also improves the accuracy of load placement
- Reduces material damage caused by incidental contact of swinging loads
- Enhances safety in operations and reduces the potential for personnel injuries and damage to equipment
- Reduces maintenance costs and downtime by decreasing stresses on structural, mechanical, and control components

# SCS SERIES 2 HAS BEEN DESIGNED TO:

- Require only one IMPULSE Variable Frequency Drive (VFD) per traverse motion with SCS software. Additional IMPULSE VFDs are connected in a Master/Slave fashion
- Operate in V/f, Open Loop Vector, and Flux Vector control methods
- Be compatible with existing master switch and radio control configurations such as Multi-step and Infinitely Variable Uni-polar/Bi-polar analog
- Eliminate the need for an external programmable logic controller
- Accept a hook height measurement when combined with an IMPULSE•VG+ Series 4 hoist drive
- Eliminate the need for a high maintenance feedback device such as an absolute encoder. The system can also be configured to operate in an operating hook height zone
- Work with multiple hoists on the same bridge

## PERFORMANCE FEATURES INCLUDE:

- Optional inputs available to fine tune the pendulum length when using multiple below the hook attachments or varying load sizes
- Automatic hook height measurement when combined with an IMPULSE•VG+ Series 4 hoist
- Seamless integration with special functions within IMPULSE variable frequency drives such as Micro-Speed<sup>™</sup> and Reverse Plug Simulation<sup>™</sup>, end of travel slow down, and stop limits
- Enabling or disabling with the flip of a switch